UniX AI

Company Introduction

With a global perspective on technology

Full-stack, general-purpose, embodied intelligence company

ROBOT FOR ALL

UniX AI

Company Introduction

Robot for all



UniX AI's Wanda Took First and Second Place

The "Wanda" series of robots independently developed by Youliqi stood out in the fierce international competition with full marks, successfully winning two gold and one silver,the second place in the gold medal list, showing the top technical strength.

2 GOLD

1 SILVER

TIMELINE DEVELOPMENT HISTORY

development history

Continuous breakthroughs • A promising future



Company Profile

With a Global Perspective on Technology

Full-Stack, General-Purpose, Embodied Intelligence Company

UniX AI , founded in April 2024, is a global full-stack general-purpose embodied intelligence technology company. With its vision of "Robot for All", the company focuses on independent R&D and multi-scenario implementation of general-purpose humanoid robots. It has established a comprehensive technical system covering electric drive, sensing, control, and model algorithms. Its products have been applied in service, security, retail, and scientific research scenarios, continuously driving the large-scale development of embodied intelligence.

The core team brings together top talents from world-class institutions such as Yale University and Shanghai Jiao Tong University, as well as leading international technology and manufacturing enterprises like Huawei, DJI, and Bosch, comprehensively covering algorithm development, system engineering, product definition, and global Supply chain and other key areas.

Full-stack in-house development
Core Algorithms and Hardware Autonomy

Generalization ability
L2/L4 level of automated adaptability

Scale production
Mature mass production and delivery system

Multi-scenario implementation
Home/General Business/Security/Research

Key Data Metrics

140 +
Global team members

70 % +
R&D personnel ratio

20 +
Industry leader

400 +
Publish papers at the summit

Average industry experience
Led by a team of expert specialists
7 Year+

Core team

Gather top-tier global talents to build a professional team, combining elite AI robotics scholars with seasoned industry experts



Fred Yang

Founder & CEO

Professional Background and Achievements

- Ph.D. from Yale University, B.S. in Computer Science and Business from the University of Michigan
- Outstanding Undergraduate Scientist of the North American Computer Association (the first one from the University of Michigan)
- He studied under Aaron Dollar, a world-renowned robotics manipulator expert at Yale University, and Alex Wong, a world-renowned robotics perception expert.
- A world-class expert in the field of visual-tactile and **the first author of UniTouch, the world's first multimodal tactile large mode**
- **As the first author, he built Touch and Go, the world's largest visual-tactile data set,**which is an important benchmark for visual-tactile pre-training models
- Published 15+ papers at leading computer vision conferences including CVPR, ICCV, ECCV, and NeurIPS.

2024 Forbes China 30 Under 30

Core team

Gather top-tier global talents to build a professional team, combining elite AI robotics scholars with seasoned industry experts



Wang Hesheng

Chief Scientist of UniX AI

Professional Background and Achievements

- Professor Emeritus at Shanghai Jiao Tong University, Dean of Pujiang International College
- **Recipient of the National Science Fund for Distinguished Young Scholars**
- **The only Chinese national president of the world's top three robotics conferences (IROS 2025)**
- The first authoritative expert in China to conduct research on robotics
- World's top expert in visual servoing and flexible object manipulation
- Expert in robot control, computer vision, and reinforcement learning control

Participated in multiple important events and presentations, receiving care from leaders at all levels



Ding Zhongli

Vice Chairman of the Standing Committee of the National People's Congress



Xin Changxing

Secretary of the Jiangsu Provincial Party Committee



Liu Xiaotao

Governor of Jiangsu Province



Xu Kunlin

Secretary of the Liaoning ProvincialCommittee



Shi Xiaolin

Vice Governor and Governor of the Sichuan Provincial Committee of the Communist Party of China.



Fan Bo

Member of the Standing Committee of the Jiangsu Provincial Party Committee, Secretary of the Suzhou Municipal Party Committee



Zuo Yongxiang

Member of the Standing Committee of the Sichuan Provincial Party Committee, Secretary of the Mianyang Municipal Party Committee



Xie Shaofeng

Chief Engineer of the Ministry of Industry and Information Technology



Xu Xiaolan

Deputy Minister of Industry and Information Technology



Zhang Yunming

Deputy Minister of Industry and Information Technology

Core Achievements and Milestones

The Double Verification of Capital Favors, Championship and Mass Production

Financing and capital recognition

Completed more than seven rounds of financing, with a total amount of **more than 500 million RMB,** and received support from many top institutions.

The honor of the World Championship

2025 World Humanoid Robot Competition: First and second place in the Hotel Service Challenge, first place in the Reception Service Challenge, **second place in the Global Gold Medal List.**

Mass Production and Key Metrics (KEY METRICS)

Mass production delivery

Hundreds units delivered

Mass production to be achieved by 2025

Product Family

4 Series

Wanda、Panther 、Martian、Pioneer

core model

3 Items

UniTouch/Flex/Cortex

Development speed

5 Months

Complete prototype development

Commercialization strategy

Global Commercial Deployment



Property security



Commercial hotel



Supermarket retail



Culture,Entertainment, and Tourism



Scientific Research and Education



Healthcare and Nursing



Reception Guide

UniX AI

Product Presentation

Robot for all

SERIES 2.0

Wanda 2.0 Full-Size Humanoid Robot

Universal embodied intelligence platform for all scenarios

Body Height

1420-1680 mm

adaptive height adjustment

DOF

33

degrees of freedom Minimum

Bionic Robotic Arm

8 DoF per arm

Dual-arm payload 12kg

Mobile Speed

90 m/min

Wheeled chassis drive

8-16 h

Ultra-long battery life

Supports fast charging



2 DOF head

Chassis System

HD binocular camera

RGBD camera

Ring six-microphone array

Minimum passage space

75cm

Ultrasonic sensor

8-DOF bionic arm

Dual-arm payload: 12 kg

Single-arm reach: 982 mm

Vertical Lift

Lift height 260mm

End Effector

Adaptive five-finger

dexterous hand/gripper

High-density battery

Battery life 8-16h

Support return charging/direct charging/battery swapping

Chassis System

360° LiDAR

Ultrasonic sensors

Moving speed90m/min

Panther

Panther Full-Size Humanoid Robot

High-end intelligent terminal for new retail and display interaction

Body Height
1600 mm
golden ratio size

Vertical Lift Height
800 mm
flexible adaptation to working height

Single Arm Reach
982 mm
ultra-large working coverage

Chassis Speed
2.0 m/s
rapid mobility capability

effective load of arm
12 kg
heavy duty support

Head movement
Left and right ± 90 °, up 20 °, down 86 °
The head has a wide range of motion

four-wheel drive omnidirectional wheel system

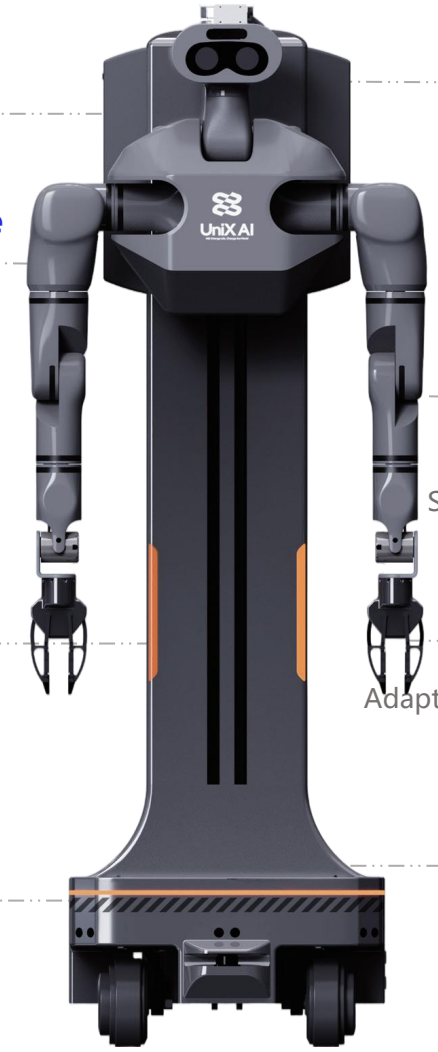
The chassis is equipped with four omnidirectional wheels (eight motors), enabling lateral movement and on-the-spot rotation for agile maneuverability.

2 DOF head

Minimum passage space
75cm

Vertical Lift
Lift height 800mm

High-density battery
Battery life 8-16h
Support return charging/direct charging/battery swapping



Chassis System
HD binocular camera
RGBD camera
Ring six-microphone array

Eight-Degree-of-Freedom Bionic Arm
Dual-arm payload 12kg
Single arm reach 982mm

End Effector
Adaptive five-finger dexterous hand/gripper

Chassis System
360° LiDAR
Ultrasonic sensors
Moving speed2.0m/s

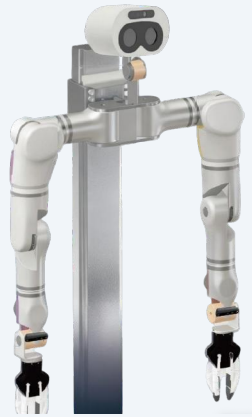
High-performance embodied intelligence robot specially built for complex commercial scenarios

CORE COMPONENT

Openarm Robotic Arm Specifications

High-performance universal robotic arm development platform

ROS2 Native



Openarm

Openarm Modular · Lightweight · High Precision

Ultimate Flexibility

8DoF

Single arm 8-DOF redundant design, simulating human hand operation space

Hardware Specifications

Arm Length **982** mm	End Effector Payload **6** kg	Repeat Positioning Accuracy **≤0.5** mm
Single Arm Weight **7** kg	Communication Protocol **CAN 2.0**	Joint Modules **Self-developed integrated**

System and Development Ecosystem

ROS2 System
Native support, seamlessly integrating into robot ecosystem

High-Performance Computing
Support NVIDIA Jetson NX / AGX

SDK Fully Open
Provides rich low-level interfaces and development documentation

Algorithm Friendly
Suitable for scientific research teaching and secondary development

CORE COMPONENT

Martian bipedal humanoid robot

Martian Martian integrates cutting-edge technologies, combining perception with large-scale models, with all core components developed in-house. Its self-developed high-performance vector control technology ensures precise control and rapid response for every joint, positioning it as a future-oriented universal embodied intelligence platform.

Basic Specs

Total height of the machine	160 cm
Total weight of the machine	50 kg
Translational speed	3 m/s (Max)
joint torque	450 N.m (Max)

Performance

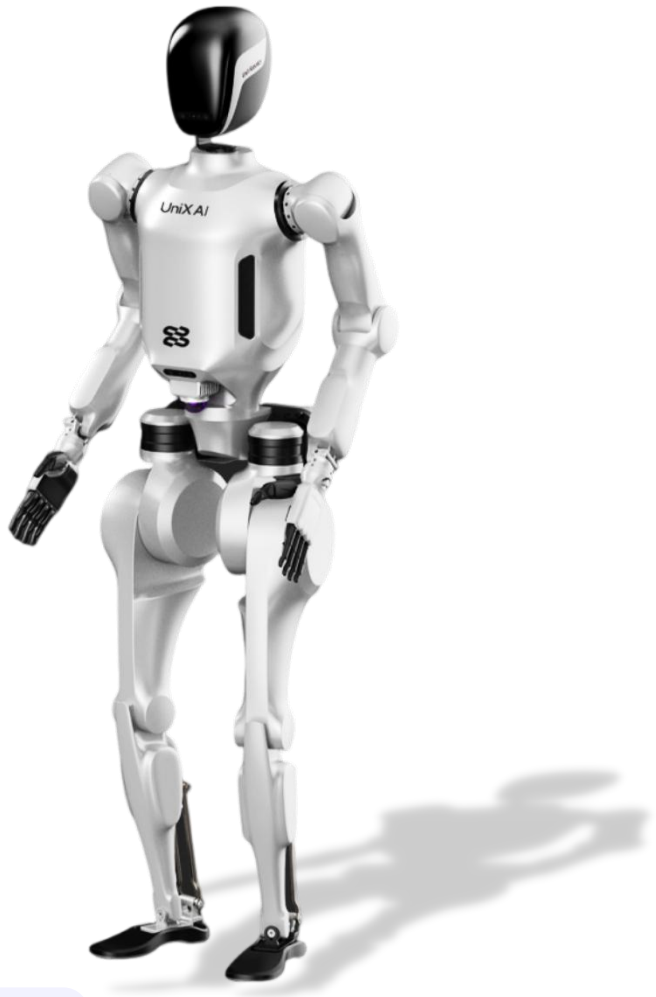
load of the whole machine	30-50 kg
Communication bus	EtherCAT
Battery capacity	9 Ah
working voltage	57.6V (Max 67.2V)

DOF Config

single leg degree of freedom	6 DOF
Single arm degree of freedom	7 DOF (五指灵巧手)
Lumbar freedom	3 DOF
head degree of freedom	2 DOF

Dimensions

Leg length	450 mm
Length of the lower leg	450 mm
Upper arm length	300 mm
length of forearm	300 mm



40T computing platform | 32GB of memory | Depth camera + RGB×2 + IMU | API open interface | OTA remote upgrade

Pioneer Series 先锋系列四足产品

Pioneer-C



Pioneer-C 01

Small but powerful, with performance that surpasses its class.

A compact industrial-grade quadruped robot with all-terrain adaptability and exceptional maneuverability, setting a new benchmark for lightweight embodied intelligence.

All-Terrain | IP54 protection | high performance

Pioneer-H



Pioneer-H 02

Break boundaries and reshape possibilities

A lightweight, high-load, fully-protected quadruped robot. Specifically designed for complex industrial environments, it balances strength and flexibility.

high capacity | Full protection | Long battery life

Pioneer-W



Pioneer-W 03

Dynamic and powerful, racing without limits

Small industry-class wheeled quadruped robot. Combining the advantages of wheeled speed and leg obstacle-crossing, it achieves efficient and stable mobile operations.

pseudopod compound | Move quickly | Ultra quiet

Pioneer-C quadrupedal product



Max Speed	Payload	Climb	Torque
3.7 m/s	8 kg	40 °	48 N.m

Quadruped • Industry Grade

Pioneer-C

Small but powerful performance beyond its class

The first small-scale industry-grade quadruped robot

All-terrain as if on flat ground
Self-awareness and target tracking, adapting to complex environments

All protection, long-lasting and durable
IP 54 protection rating, resistant to dust and water splashes

All-weather scenario adaptation
0Operating temperature range of approximately 40°C

Multi-platform support
Open SDK, supports secondary development

Technical Specifications — **100 TOPS Compute**

Standing height (cm)	Folding size (cm)	Total weight of the machine
63 × 66 × 41.5	67 × 42.5 × 14.5	15 kg (including battery)
Battery parameters	**Range/Time**	**Continuous climbing height**
5Ah / 43.2V	6 km / 1-2 h	16 cm

Navigation settings

Jetson Orin NX 16G	Mid360° LiDAR	Realsense Depth Camera

Pioneer-H quadrupedal product



MAX SPEED	PAYLOAD	CLIMB	OBSTACLE
8m/s	30kg	45°	80cm

QUADRUPED • Heavy Duty

Pioneer-H

Break boundaries and reshape possibilities

Lightweight, High-Load, Fully Protected Quadruped Robot

strongest load in the same class
30kg periodic steady-state/high-speed exercise load

The strongest protection in its class
IP67 rating, operating temperature range of-20 to 55°C

The best battery life in its class
Dual battery hot-swappable, mission uninterrupted

The strongest expansion in its class
15 interfaces for secondary development

TECHNICAL SPECIFICATIONS

Wheel/foot switch support

Standing height (cm) **92 × 48 × 57**	Folding size (cm) **93 × 63 × 20**	Total weight of the machine **30 kg (Full Foot Version)**
Battery capacity **20 Ah (Dual batteries)**	Battery life **> 3.5 h**	Levels of protection **IP67 (-20~55°C)**

External expansion interfaces (15)

Gigabit network port | USB/gorge line | 5/12/24/48V power supply | 480W Max

Pioneer-W quadrupedal product



MAX SPEED	MAX RANGE	OBSTACLE	TORQUE
5.5 m/s	9 km	65 cm	48 N.m

WHEELED QUADRUPED • Hybrid Mobility

Pioneer-W

Dynamic and powerful, racing without limits | Small-scale industrial wheeled quadruped robot

all-terrain obstacle crossing
Wheel-based rapid maneuverability and foot-based obstacle-crossing flexibility

All protection, long-lasting and durable
IP 54 protection rating, operating temperature range: 0 to 40°C

Mission endurance improved
Battery life improves by approximately 50%, enabling extended operational range

Run silently
No "beep-beep" noise interference, seamlessly integrated into the research environment

TECHNICAL SPECIFICATIONS — SDK Support

Standing height (cm) **63 × 44 × 45.5**	Folding size (cm) **69 × 58 × 14.5**	Total weight of the machine **20 kg (With batteries)**
Battery/Duration **5Ah / 1-2h**	Critical load **≈ 12 kg**	Maximum climbing angle **40°**

external expansion interface

Gigabit network port | USB/gorge line | 5/12/24/48V power supply | 480W Max

Core Algorithm Platform

Three core engines driving embodied intelligence evolution

Core Technology

Efficient Imitation

UniFlex Architecture

Architecture specifically designed for embodied intelligence, greatly reducing task learning threshold by decoupling perception and manipulation models.

EFFICIENCY

5-10 Times

Complete Complex Task Learning

World-leading

UniTouch Platform

Multi-modal large model with extremely strong general capabilities, deeply integrating visual, linguistic, and tactile information, endowing robots with environmental understanding.

Vision | Language | Touch

Multimodal fusion perception

Long Sequence Planning

UniCortex Model

The decision-making center of robots, with powerful logical reasoning capabilities, achieving precise mapping from natural language instructions to continuous actions.

MAPPING

Instruction → Action

End-to-End Planning

CORE ARCHITECTURE

UniFlex Architecture Deep Dive

Decoupling perception and manipulation, redefining the embodied intelligence learning paradigm

Minimal Demos

5-10 Times

Low-cost data collection
Fast task deployment

UniFlex Core Engine

Perception Model

Visual / Tactile / Depth information extraction

Anti-interference

Decoupled architecture

Manipulation Model

Trajectory planning / Force control / Motion primitives

High generalization

Multi-Task

Multi-scenario compatible

Strong Robustness

Fast Learning Efficiency

Only 5-10 demonstrations needed to master new skills, breaking through the bottleneck of traditional robots requiring massive data training.

Multi-modal Anti-interference

Perception and manipulation are decoupled. When environmental lighting and object colors change, the manipulation model remains stable, unaffected by visual noise.

Full-Scenario Adaptation

Modular design enables core capabilities to be quickly migrated, widely adapting to various complex scenarios such as home, commercial, and industrial.

机器人系统构成

全栈式软硬一体化架构

system architecture

Brain & Cloud

UniCortex Model
general embodied intelligence brain

Cloud Computing Platform
Massive computing power support

Multimodal Large Model
General Understanding & Reasoning

Data & Control Flow

Core Platform

UniFlex Architecture
System

Flexible System Scheduling and Whole-body Control Framework

UniTouch Platform
Interaction

for refined operations and tactile perception processing

Hardware



Wanda 2.0



Panther



Openarm



Martian



Pioneer-C



Pioneer-H



Pioneer-W

UniX AI

Scenario-Based Applications

Robot for all

SCENARIOS PART 1

Property Security Scenario Application

In the scenario application of property security, the robot can autonomously plan the path, carry out **inspection of fire room,stairwell, tea room and toilet,** support multi-task parallel and dynamic adjustment, flexibly adapt to environmental changes, and comprehensively ensure property security and environmental health.



Inspection of fire compartment

- fire alarm equipment inspection
- Fire hydrant facility inspection
- Fire door function test
- Verification of positive pressure air supply port status
- Smoke alarm status confirmation

Patrol the stairwell

- Inspection of corridor lighting and signage
- Door closure and lighting status
- Integrity Verification of Anti-riot Equipment
- Channel anomaly troubleshooting

Tea room inspection

- Light inspection
- Verify the water dispenser power supply
- Check the faucet status
- Clean up the trash on the countertop.

Toilet Inspection

- Inspection of faucet and countertop
- Verification of the Function of the Switching Door and Lighting

SCENARIOS PART 2

Hotel service scenario application

Welcome Reception

Smart voice greets guests, provides check-in guidance and facility introductions, and creates a professional first impression.

Room Service

24/7 autonomous delivery of goods and tea to meet guest room requests, ensuring privacy and convenience.

Room Cleaning

Based on the standardized SOP for human-machine collaboration, tasks such as ground cleaning and garbage disposal are performed to enhance hygiene standards.

Security Patrol

24/7 scheduled patrols of floors and public areas automatically detect anomalies and trigger real-time alerts to ensure hotel safety.





SCENARIOS PART 3

Supermarket retail scenario application

In the application of supermarket retail scenarios,robots can achieve intelligent replenishment, intelligent pickup, supermarket inspection, product recommendation and other functions, which can comprehensively improve operational efficiency and customer experience.



Smart pickup

- Automatically identify product location
- Precisely capture target items
- Reduce labor costs for picking

Smart restocking

- Automatically identify out-of-stock areas
- Supplement on demand
- Optimize inventory management efficiency

Supermarket inspection

- Check the store environment regularly
- Detecting abnormal conditions
- Ensure the safe operation of supermarkets

Recommended Products

- Personalized product recommendations
- Promotion Message Broadcast
- Enhance customer shopping experience

Cultural and entertainment scene applications

For cultural tourism and entertainment scenarios, the robot integrates the whole chain functions from tour guide, route recommendation to entertainment interaction, effectively serving tourists with intelligent solutions, and significantly improving the fun and commercial value of the place by leveraging brand IP value-added.









Application of Robot in Tourism Scene

Scenic Area Guide

- Multilingual automatic switching explanation
- Historical anecdotes are vividly told
- Real-time update of the event schedule

Route recommendations

- Intelligent recommendation of surrounding services
- Customized theme tour route planning
- Creation of an interactive audience atmosphere

Performance event

- Drumming, guzheng performance, etc.
- Special Festival Theme Performance
- Creation of an interactive audience atmosphere

Brand IP value-added

- Customized appearance of the IP image
- Social media interaction-driven traffic generation
- Enhancing brand image through technological elements

SCENARIOS PART 5

Research and education scenario application

In the field of scientific research and education, we are committed to jointly building robot training bases with colleges and universities, and deeply support robot competitions, vocational training and joint product development to promote the integration of industry, university and research.



Co-developing Courses

- Joint Development of Teaching Resources by School and Enterprise
- Bring real projects into the classroom
- Reconstruction of Curriculum System of Industry Orientation
- Enterprise Mentors in the Classroom

Dual-Teacher Development

- Mutual appointment of teachers and sharing of teaching staff between school and enterprise
- Synergistic Development of Scientific Research and Teaching
- Teacher Enterprise Practice Flow Station
- Research Feedback Teaching Mechanism

Training base

- National Industry-Education Integration Base
- Open Innovation Lab
- Full-chain training of robot industry
- realistic production scenario replication

Position Competition Certificate

- Innovation and Entrepreneurship Competition Project Guidance
- Industrial Training and On-the-job Practice
- Vocational Skill Level Certificate Training
- High-quality employment express service

Application of Nursing Care Scenarios

In the field of health care, robots provide daily living assistance,warm emotional companionship and continuous environmental safety monitoring to comprehensively improve the quality of life, security and physical and mental health of the elderly.

01

Assistance With Daily Living Activities

- ✓ Scheduled Automatic Distribution
- ✓ High Precision Autonomous Navigation and Delivery
- ✓ Personalized Schedule and Medication Reminder
- ✓ basic consolidation and auxiliary labor sharing





02

Emotional Companionship and Health Care

- ✓ Personalized Content Accompaniment and Natural Interaction
- ✓ Fun interactive and cognitive promotion activities
- ✓ Health Care and Equipment Operation Assistance
- ✓ Human-machine collaboration enhances the quality of nursing services





03

Environmental Security Patrol

- ✓ 24/7 unattended inspection
- ✓ Integrated Patrol with Multiple Tasks
- ✓ Accurate Identification of Abnormal Behavior and Risk
- ✓ Condition Monitoring and Real-time Reporting of Facilities





SCENARIOS PART 7

Reception and Introduction Scenario

For the reception and explanation scenario, the robot provides intelligent services throughout the whole process, from welcoming guests, interactive performance to professional exhibition point explanation, creating a professional, friendly and full of technology visiting experience through multimodal interaction technology.



Welcome Service

- Intelligent voice greeting
- Welcome Talent Show
- Guided route service
- Switch multilingual welcome messages

Interactive performance

- Delivering water and goods with thoughtful service
- Showcase of playing the piano and drumming skills
- Fun game interactive experience
- Real-time Q&A interaction

Exhibition Point Explanation

- Detailed introduction to the exhibits
- Display multimedia content synchronously
- Interactive Q&A
- The lecture content is updated in real time

UniX AI

Cooperation Case

Robot for all

CASE STUDIES

Case Studies

UniX' s Robotics implements real-world scenarios to empower partners' intelligent transformation

Zhongxin Building



Office Business Scenario

UniX' s Robotics has officially commenced operations at Zhongxin Building. The deployment of its wheeled dual-arm robots delivers comprehensive and highly efficient intelligent services, significantly enhancing the building's technological sophistication and service quality.

Key Application Features

- Welcome and Guidance
- customer service
- package delivery
- Hall inspection
- Exhibition Hall Guide

Fonterra Sheraton Hotel



High-End Hotel Scenario

To become the "new partner" in daily hotel operations. Robots can not only actively identify guests in the lobby for communication and guidance, but also use dexterous hands to deliver meals with precision in the restaurant, creating an experience that blends warmth with technology.

Key Application Features

- Active communication guidance
- Assist with welcoming guests
- The restaurant's skilled staff delivers meals with precision.

Joint Practice of Sichuan Province Embodied Intelligent Robot Training Field

project context

The first provincial-level embodied intelligent robot training platform in western China, led by Sichuan Changhong, has been established to address the needs of real-world training, data collection, and application validation for embodied intelligent robots, creating multi-scenario training spaces.

Core roles of UniX AI

Design of Scenario-based Training Process

Decompose real-world business and industrial tasks into executable training processes to support continuous task execution.

Multimodal Data Acquisition and Training

The organization of remote operation collection, task replay and inference testing, to form high-quality training data.

Application demo and implementation verification

Support robot operation in factory and retail environment to verify stability and application capability.

Typical scenario results

Business and Public Services

Guide and interactive task training to verify the ability of complex human-computer interaction.

Industrial Manufacturing Scenario

Training in skills like scanning codes, labeling, and material handling to verify precise operations.



Training ground exterior view



Show Hall


Training environment


VR remote operation demonstration



Multimodal acquisition

Practice of Suzhou Embodied Intelligent Robot Comprehensive Innovation Center

project context

Suzhou has established a flagship innovation platform for embodied intelligent robots, featuring capabilities in real-world scenario training,simulation validation, and large-scale training, providing system-level training and validation services for end-user enterprises.

Core roles of UniX AI

Constructing Continuous Task Training and Demonstration Scenarios
In real-world environments like supermarkets and home furnishing stores, robots are deployed to perform continuous multi-task operations including restocking, organizing, and cleaning.

Verify the stable operation capability of complex environments
The robot's comprehensive performance of environment understanding, task planning and execution stability is highlighted.

Experience in cross-scenario training and demonstration of sedimentation
The key process and method are transformed into reusable training and practical design experience.

Show Results

Concurrent execution of multiple tasks
The multi-scenario and multi-task continuous execution capability and the stable performance in real environment.

Capability validation
Scenario-based training is an intuitive verification of the overall capability of the system.


Outlook of the Innovation Center


Leadership Inspection and Exchange


Live demo


Robot Service Demo

Cooperation Case

Join hands with leading enterprises to create a new ecosystem of embodied intelligence

Educational Research

清華大學

南京大學 NANJING UNIVERSITY

東南大學 SOUTHEAST UNIVERSITY

西安交通大學 XI'AN JIAOTONG UNIVERSITY

上海交通大學 Shanghai Jiao Tong University

浙江大學 ZHEJIANG UNIVERSITY

南京工业职业技术大学

济南工程职业技术学院 JINAN ENGINEERING VOCATIONAL TECHNICAL COLLEGE

中国科学院自动化研究所 INSTITUTE OF AUTOMATION CHINESE ACADEMY OF SCIENCES

Yale University

Massachusetts Institute of Technology

Cornell University

Business Scenario

中国石油

KFC

Tantai Lake

Sheraton HOTELS & RESORTS

百胜 YumChina

CSSD 中新集团·旗下企业 | hq 中新和存

Hilton HOTELS & RESORTS

美宜佳

CHANGHONG 长虹

智汇苏州·链动未来 苏州市具身智能机器人综合创新中心

四川省具身智能机器人创新中心

上海浦东国际机场 SHANGHAI PUDONG INTERNATIONAL AIRPORT

EMPOWERING THE FUTURE

UNIX AI
TECHNOLOGY

Robot For All

A full-stack general embodied intelligence company with global technical vision.



OUR MISSION
Building A New Intelligent World
For Humanity Through Innovative Technology.

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